### NDSF Data Manager Report

# NDSF Data Management Structure







NDSF DATA MANAGEMENT

SENTRY World 16th Cherangraphic Institution

(1) Video and Imaging Systems (2) Real-Time Data Logging and Display (3)
Pre-Cruise and
Post-Cruise
Coordination

(4) At-Sea Processing Pipeline and QC (5) Processing Tools





NDSF Data Archives





## Standard NDSF Data Deliverables...

- Offer prospective vehicle users information necessary for pre-cruise planning
- Impose responsibility guidelines on NDSF
- Assure a departing chief scientist that she or he has received the expected collective of data
- Serve the larger ocean science community by ensuring that products of consistent content and quality are available long after the initial science studies have concluded









# Data Deliverables: © Commonalities Among the Vehicles

- Software DVLNav (Whitcomb and Kinsey) collects, and processes (ROV/AUV), navigational data. Integrates ship and vehicle data, acoustic LBL if deployed, DVL.
- Real-time/raw data: time, position, heading, pitch, roll, depth, altitude, temperature, salinity, magnetometer (optional on Alvin)
- Imaging: video and stills from digital camera, bathymetric sonar if requested
- Autosnaps and events: framegrabbed video coregistered with sensor data
- Archived in accordance with WHOI Archive Policy; hard media archived at WHOI Data Library









## Data Deliverables: Alvin Specifics

#### Straight from the vehicle

- Raw sensor logs
- DVLNav logs
- -Framegrabber: framegrabbed video (30 sec) from two external digital cameras, coregistered w/ vehicle nav, attitude, & science instrument data

#### Digital video

- Science selects two of four external cameras, to DVCAM tape
- Ship tech makes exact copies, overlaying science's choice of realtime data & delivers these copies with standard data package









## Data Deliverables: Jason Specifics

- Raw (includes GPS & LBL) and DVLNav logs from Jason, Medea and ship
- First-order nav (merged LBL and DVL) and first-order SM2000 sonar (yielding XYZ dot cloud and 1m grid)
- Virtual Van and Event Logger: four cameras from Jason and Medea coregistered with ship and vehicle data; also science comments, if any. Online postcruise, with password access during moratorium
- Video (three Jason cameras), to DVD
  - Science copies are overlayed with selection of real-time fields
  - Archive copies are not overlayed, but they carry the info









## Data Deliverables: AUV Specifics

- Nav: first-order processing; LBL merged with DVL, recalibrated compass and magnetometer
- Digital still photos: .jpg
- Vehicle data coregistered with science subsystem fields; ASCII .csv
- Bathymetry
  - ABE: SM2000 sonar; raw (.smb), XYZ point cloud, gridded at 5m
  - Sentry: Reson sonar; deliverables are expected to be similar or superior to the SM2000 product









### NDSF Data Manager Report

# NDSF Data Management Structure







NDSF DATA MANAGEMENT

SENTRY World Hot Commerce to Lindings

(1) Video and Imaging Systems (2) Real-Time Data Logging and Display (3)
Pre-Cruise and
Post-Cruise
Coordination

(4) At-Sea Processing Pipeline and QC (5) Processing Tools





NDSF Data Archives





## (1) Video and Imaging Systems

- Improved cameras (Lange)
- Revisiting lighting (Lange)
- Video is a standard product
  - Do we require science to provide personnel to run Jason DVD decks for archive video?









## (2) Real-Time Data Logging and Display

#### Vehicle Metadata Standardization

 Transmit to beach and make available (and harvestable) during cruise via xml files

#### Event Logger Update

- Address the backbone of how data are organized
- Sampling metadata (MGDS vocabulary)
- NDSF vocabulary consultation in 2008

#### Virtual Van/FrameGrabber

- Alvin renav ingestion
  - AT11-07, AT11-10, AT11-13, AT11-20, AT11-26
- Provide *Jason* data by lowering (testing)









# (3) Pre-Cruise/Post-Cruise Coordination Archives

- Coherent pan-NDSF backbone data structure is critical
- Evaluate management of all vehicle data on one server (RAID drive) by NDSF Data Manager
  - Dive metadata
  - Vehicle data
- Parallel RAID drive at NDSF/WHOI Archive
  - Long-term goal 1: make data available online
  - Long-term goal 2: remote data archive









## (4) At-Sea Processing Pipeline/QC

- Organize all NDSF vehicle data at sea by lowering
  - Data deliverables provided to science and archive by lowering/dive
  - Archived Jason data also preserved by day
- Hard drive backups now standard for Jason dives in addition to DVDs
- Longevity of DVDs?
  - 90 examined from 2003: found 3 with read errors









## (4) At-Sea Processing Pipeline/QC

- Nav QC
  - Jason nav processing at sea
  - Automated scripts for use in field have been developed (J. Kinsey) and are ready for testing
- Sonar QC
  - Jason sonar processing at sea
- New QC scripts will be built to leverage digital metadata acquired for each dive



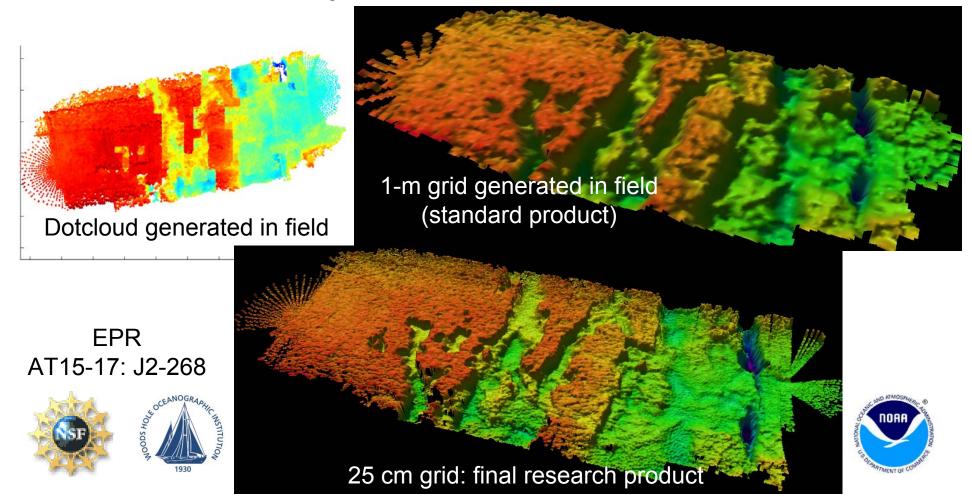






# (4) At-Sea Processing Pipeline/QC

 At-sea processing = standard data products only - not final research products



## (5) Advanced Processing Tools

- Goal: put NDSF data into more generic formats for processing with other tools
- Continue to support existing DSL software
- Sonar
  - − MB System ⇒ Caris Hips and Sips
- Photomosaics
  - Use existing DSL mosaicking code for better georeferencing for individual images in large area down-looking mosaics
  - Make UNH video mosaicking software available









## **Questions for DESSC**

- Should the magnetometer be a standard sensor for all vehicles?
  - If so, do we require calibration turns for each dive/lowering?







