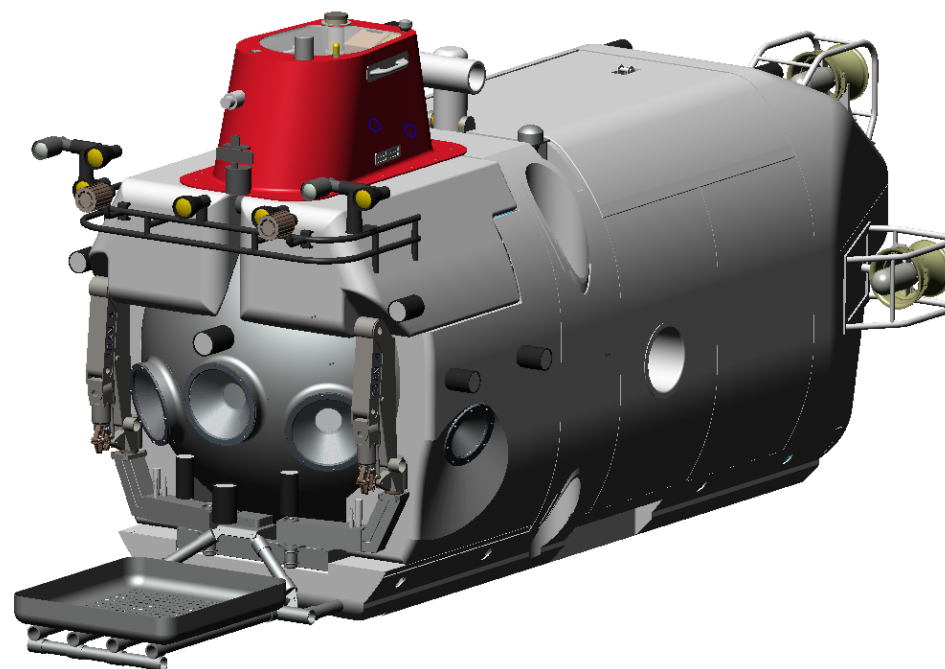


# Replacement Human Occupied Vehicle

## DESSC Update

December 9, 2007



# Replacement HOV Update

## Outline

- RHOV Management Team
- Personnel Sphere Updates
- Vehicle Updates
- Vehicle Cost Drivers
- Integrated Sphere and Vehicle Schedule



# Replacement HOV Update

# Changes to the Management Team

## Program Manager

**Tom Lewis**

*Naval Sea Systems Command 1983 - 2007*

- Special Operating Forces Undersea Mobility Office
- Deep Submergence Program Office
- Submarine Safety and Quality Assurance Division
- TRIDENT Submarine Program

## Assistant Program Manager

**Anthony Tarantino**

*STS International Inc. 2006 - 2007*

- In water Security Systems

*Woods Hole Oceanographic Institution 2000-2006*

- DSV Alvin Operations Group

*Bruker Federal Systems Inc. 1994-2000*

- Production/Final Test /Support Group
- Technical Transfer Team
- Prototype Service Group



## Replacement HOV Update

# Personnel Sphere Progress

- 5-6 Sep 2007: Southwest Research Institute (SwRI) submitted Detailed Design Review (DDR) for RHOV personnel sphere
- The design was reviewed and accepted by ABS and received concurrence by NAVSEA
- Subcontracts in place:
  - Ladish Forge (forging)
  - STADCO (machining and welding)
  - Bodycote Inc. (heat treatment and stress relief)
  - ABS America (certification)
- **Titanium ingots delivered, fabrication phase started!**



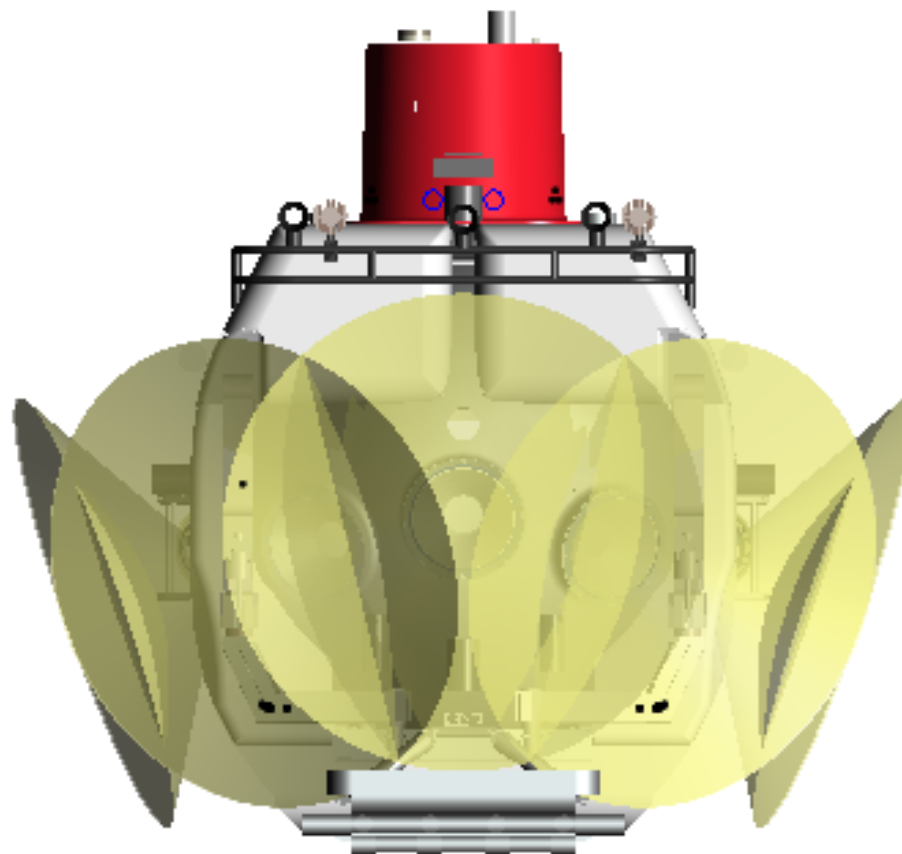
# Replacement HOV Update

# SwRI Personnel Sphere

Final Design based on  
NADAC/RHOC/DESSC input



Three 18-inch forward viewports  
Two 13-inch side viewports



Overlapping Viewing Area



# Replacement HOV Update

# Vehicle Contracting

## 8 June 2007: Lockheed Martin (LM) awarded contract for vehicle design and fabrication

### Contracting Methodology

- Collaborative effort to develop scope of work, specs, and cost estimates
- Allows both parties to develop a clear understanding of the requirements
- Will reduce risk to contractor and mitigate potential cost overruns

### Contract Structure

#### *Two Phase Contract*

- Preliminary Design and Detailed Cost Estimate of Vehicle (CLIN 1)
- Detailed Design, Fabrication, and Test of Vehicle (CLIN 2)

In order to close CLIN1, LM must provide detailed costing for CLIN 2 six weeks after completion of Preliminary Design Review (PDR), at which time price negotiations begin.

Based on the cost estimate, WHOI/NSF has the option to execute CLIN 2 or cancel contract.



# Replacement HOV Update

## Key Events

DESSC  
December 2007

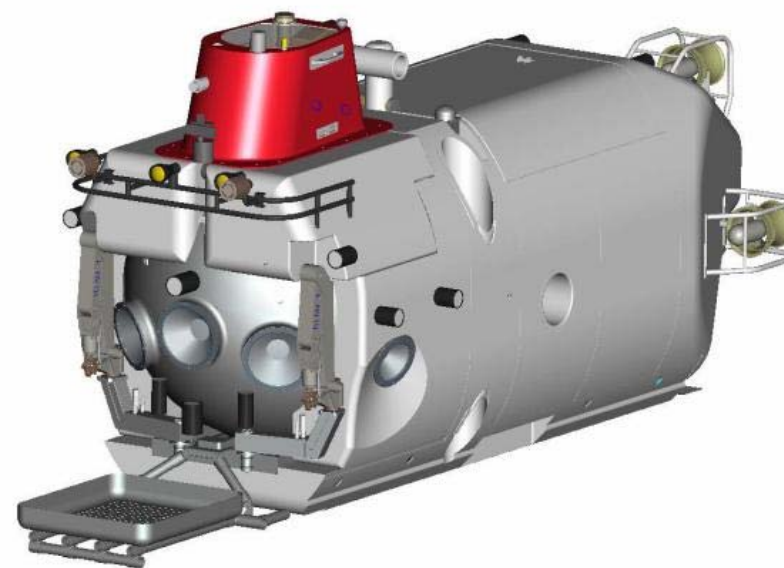
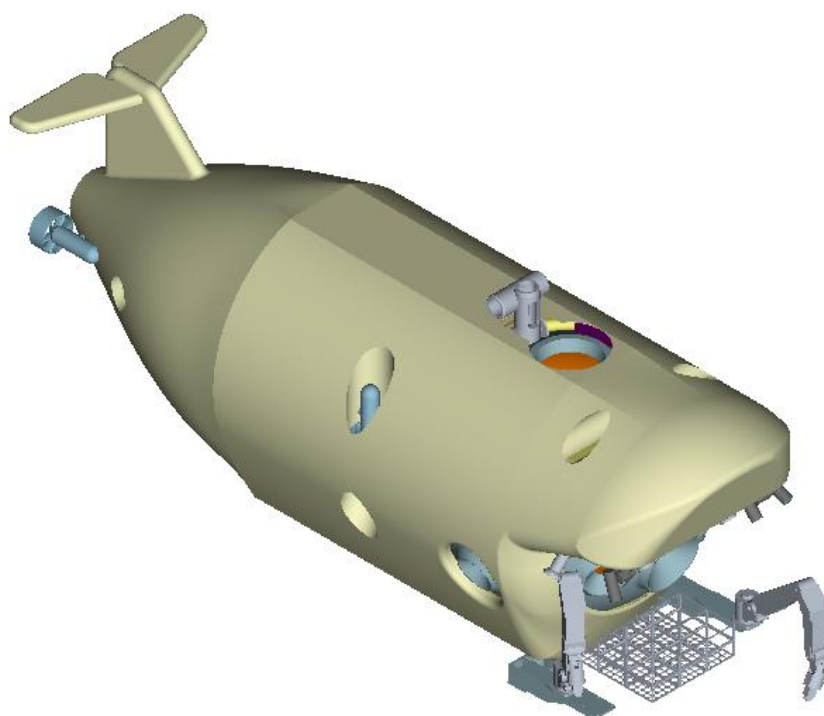
### 2007

<b>8 June</b>	Vehicle contract executed
<b>27 June - 1 July</b>	LM engineers observed operations during <i>Atlantis</i> engineering cruise
<b>24 - 25 July</b>	System Requirement Review / System Design Review conducted at LM
<b>15 - 17 October</b>	Design Team meeting with Alvin Pilots
<b>13 - 15 November</b>	Preliminary Design Review
<b>Ongoing</b>	WHOI-LM Technical Exchange



# Replacement HOV Update LM / Vehicle

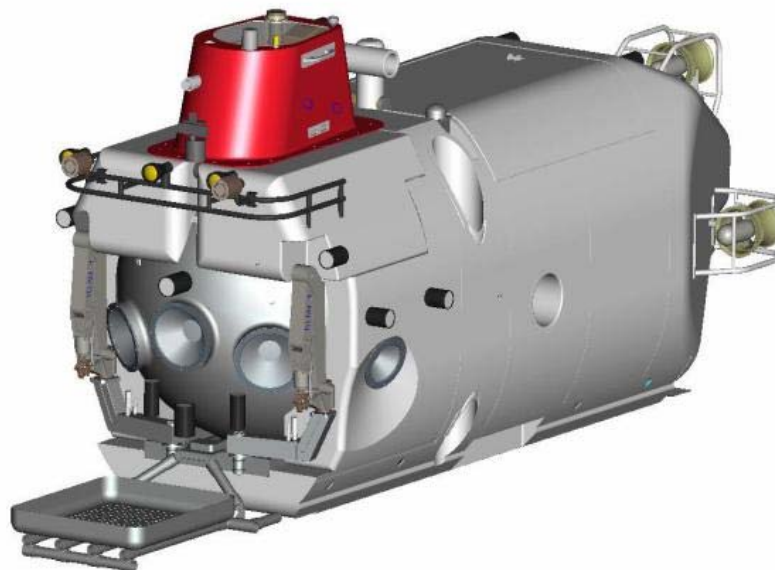
## Concept vs. PDR





# Replacement HOV Update

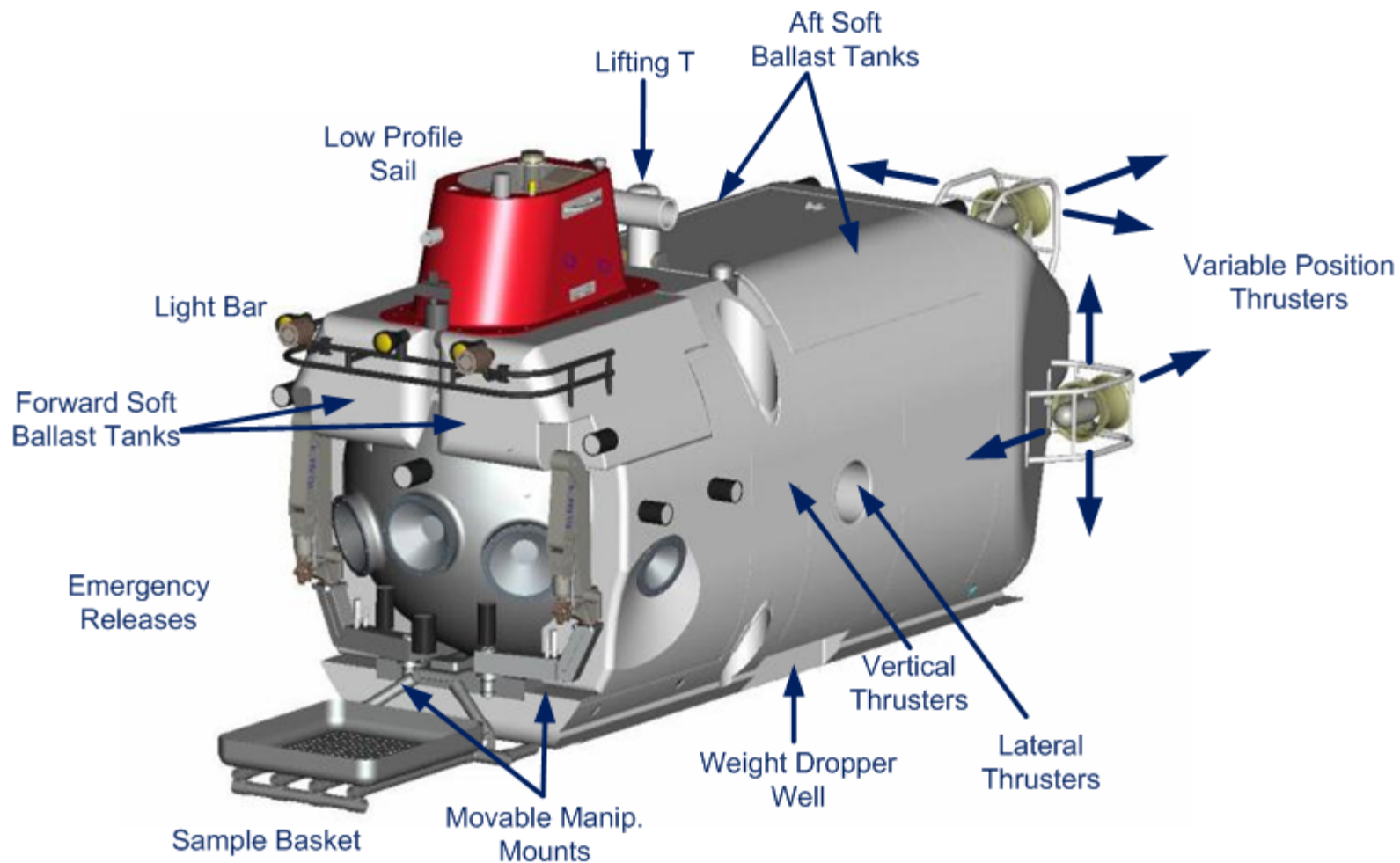
## Vehicle Characteristics



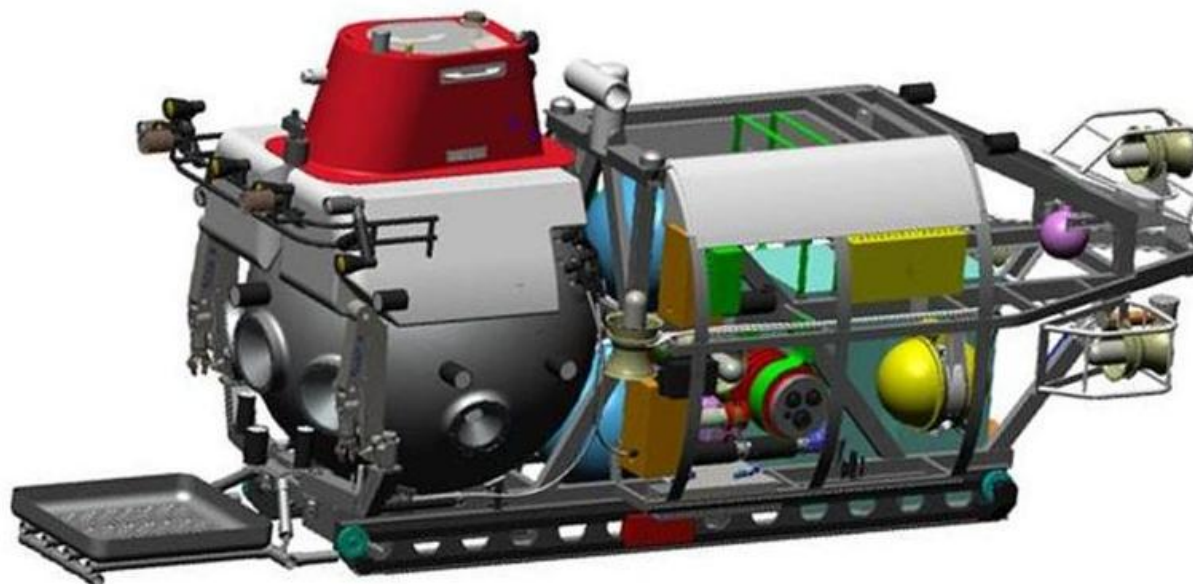
- 43,419 lbs air weight (heaviest state)
- 24' L x 7.5' W x 11.0' H
- Descent time to 2,500m = 73 min
- 7-8 hr bottom time (2,500m)
- 6 thruster configuration
- Movable manipulator mounts
- Flat top and bottom surfaces
- Low profile sail
- Compatible with current A-Frame
- Limited ship modifications
- Maintain *Atlantis/Alvin* launch & recovery procedures



# Replacement HOV Update Vehicle Arrangement



# Replacement HOV Update Vehicle Systems

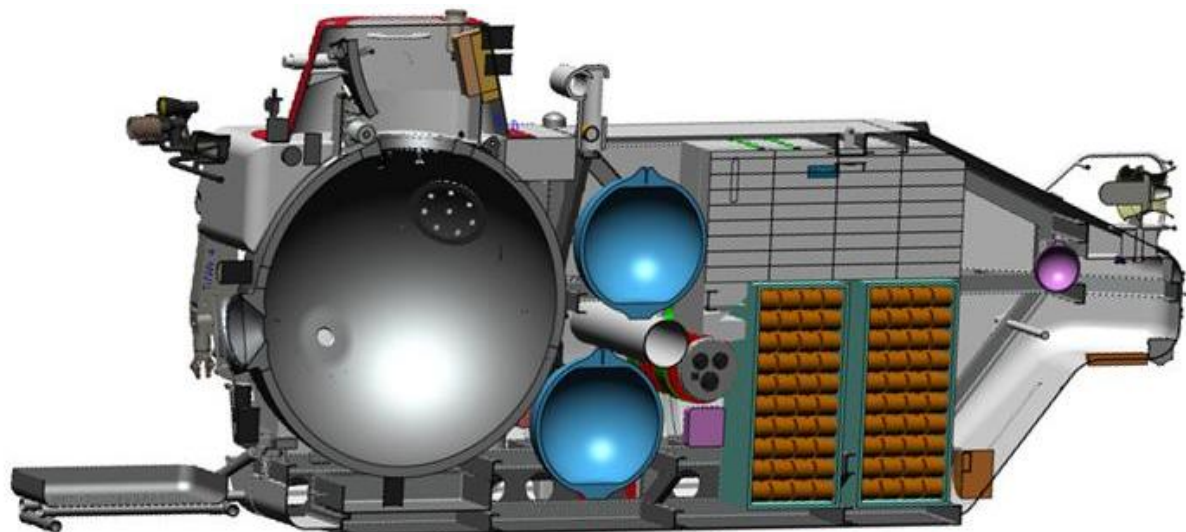


- **Soft Seawater Ballast System**
  - 4 separate tanks provide extra buoyancy for surface stability
- **Pitch Trim System**
  - 2 independent moveable weights
  - +/-10° pitch trim
- **Port and Starboard Architecture**
  - Eliminates single critical path
  - Increases reliability
- **Main Hydraulic System**
  - Up to 8 science functions
  - Backup for VB system valve actuation



# Replacement HOV Update

## Vehicle Systems (cont.)



- **Battery Distribution System**
  - Li-based battery technology
  - 2 independent battery tanks
- **Variable Ballast System**
  - Dual motor/pump combination
  - Backup motor to drive main hydraulic system pump
- **Flotation Foam**
  - Primary buoyancy
  - 250 cubic feet
- **Profiling Sonar**
  - Reson SeaBat
- **RDI Doppler Velocity Profiler**
  - DVLNav



# Replacement HOV Update

## Sphere Ergonomics



- Ergonomic design in accordance with US standards where possible (1988 US Army or NASA-STD 3000)
- Volume and interference checks done with three 95<sup>th</sup> percentile males
- “Reach limits” defined by 5<sup>th</sup> percentile female
- Adjustable controls
- Observer seating will provide optimized view and better support than pads



# Replacement HOV Update Specification Comparison

	<i>Alvin</i>	RHOV
<b>Depth</b>	4,500 m	6,500 m
<b>Sphere Volume</b>	144.2 ft <sup>3</sup>	170.8 ft <sup>3</sup>
<b>External Science Payload</b>	275 lbs	400 lbs
<b>Internal Science Payload</b>	6,630 in <sup>3</sup> 19" rack space	12,300 in <sup>3</sup> 19" rack space
<b>Max Speed (fwd)</b>	2 kts	3 kts
<b>Max speed (lateral)</b>	Minimal lateral ability	0.5 kts
<b>Max Speed (vertical)</b>	30 m/min	48 m/min
<b>Trim Angle</b>	+/- 7.5 deg	+/- 15 deg
<b>Positioning Control</b>	Manual w/ auto heading	Auto heading, DP, track and following control



# Replacement HOV Update

## Power Comparison

	<i>Alvin</i>	RHOV
<b>Chemistry</b>	Lead Acid	Lithium
<b>Dive Time</b>	9 hrs (typical)	10.5 hrs
<b>Bottom Time</b>	5-6 hrs	7.5 hrs
<b>Lifetime Cycles</b>	400 total	2,000 total
<b>Maintenance Cycle</b>	60	No scheduled maintenance
<b>Available Energy /Dive</b>	30 kW-Hrs	100 kW-Hrs

*Lead acid battery designed to meet RHOV requirements  
would exceed 10,000 lbs and 70 ft<sup>3</sup>*



## Replacement HOV Update

# Cost Drivers

- **Power Consumption**

Battery is a custom application: as power increases, battery capacity and weight increase

- **Weight**

300 ft<sup>3</sup> of syntactic foam required at a total cost for raw material of \$675,000, with additional costs for shaping, bonding and testing

- **Engineering**

ABS classification and Non Recurring Engineering (NRE) can be very costly





# Replacement HOV Update

## Cost Improvements

- **Battery**
  - Non-COTs (commercial off the shelf) solution
  - Sizable non-recurring engineering charges
  - Weight and size driver
- **Variable Ballast**
  - Power consumption (battery)
  - Overall weight (foam)
  - ABS classification impact



## Replacement HOV Update

# Batteries

*Design to 3-yr, 600 cycle vs. 10-yr 2000 cycle solution*

### Pros

- Take advantage of advances in battery technology
- Reduce energy requirement (de-rating factor)
- Reduce size and weight
- Decrease initial costs

### Cons

- Increased life-cycle costs

*Evaluate vehicle power requirements*



## Replacement HOV Update

# Variable Ballast

*Switch to a smaller capacity VB system and use drop weights for descent/ascent*

### Pros

- Maintain mid-water capabilities
- Increase safety, minimize risk, and reduce ABS requirements
- Simplifies system and reduces weight and power consumption
- Cross-deck *Alvin* seawater pump

### Cons

- Will require use of expendable ballast (similar to *Alvin*)

*Trade study underway by LM on cost, weight, power implications*



## Replacement HOV Update Path Forward

- Evaluate detailed cost estimate for design and fabrication
- Present cost estimate to RHOC/NSF, 20-21 Feb 2008
- Proceed to CLIN2



# Replacement HOV Update SwRI / LM Combined Schedule

