#### **FUTURE 2024**

FUTURE of US Marine Seafloor & Subseafloor sampling capabilities workshop March 26-28, Woods Hole, MA

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FUTURE 2024 Workshop PIs (NSF OCE #2341096)



#### Sharing knowledge

while enlightening collaborative seafloor/subseafloor sampling research opportunities among generations, science disciplines, and science/engineering/operations teams in the US

•132 in-person participants from 63 US Institutions. (inc. NSF PDs (5), speakers (10) +Future 2024 PIs (5))

"Early Career Scientists" (= $\sim$  52 %))

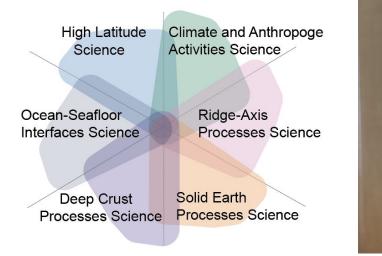
- 25 of them are obtaining PhD 2024 $\sim$
- 31 of them obtained PhD 2012-2023

•68 remote participants from both US and non-US Institutions.





#### SCIENCE-DRIVEN ASSESSMENT OF THE US OCEANOGRAPHIC/SAMPLING CAPABILITIES







•Day-1: Critical science questions that require seafloor sampling.

•Day-2: Aligning seafloor sampling technology with critical science questions.

### **WORKSHOP OUTCOMES:**

				Ocean-Seafloor Interfaces	Climate and Anthropogenic Activities	Deep Crust Processes	Ridge Axes Processes	Solid Earth Processes	High-latitude Sciences
1	The FUTURE of the US marine seafloor & subseafloor sampling capabilities (revision submitted to AGU Advances)         oppose           FUTURE 2024 PI-team <sup>1.6</sup> , Bruce Appelgate <sup>7</sup> , Brandon Dugan <sup>8</sup> , Nobuhisa Eguchi <sup>9</sup> , Daniel Fornari <sup>1</sup> , Tim Freudenthal <sup>10</sup> , Patrick Fulton <sup>11</sup> , Sean Kelley <sup>1</sup> , Susan Q. Lang <sup>1</sup> , Dana Manalang <sup>6</sup> , Alam Mix <sup>4</sup> , Rick Trask <sup>1</sup> , Janine Andrys <sup>12</sup> , Saran Beethe <sup>5</sup> , Hannan Bridgham <sup>13</sup> , Haley Cabaniss <sup>14</sup> , Sami K. Cargill <sup>5</sup> , Christian W. Conroy <sup>15</sup> , Kassandra Costa <sup>1</sup> , Alysia Cox <sup>16</sup> , Andrew Cross <sup>1</sup> , Deena Dwyer <sup>5</sup> , Justin Dodd <sup>17</sup> , Jeffrey Donnelly <sup>1</sup> , Valerie Finlayson <sup>18</sup> , Mohammed Hashim <sup>1</sup> , Daniel Heaton <sup>5</sup> , Julie Huber <sup>1</sup> , Brittany Hupp <sup>10</sup> , Matthew G. Jackson <sup>20</sup> , Claire Jasper <sup>2</sup> , Hirok Kitajma <sup>21</sup> , Olga Libman-Roshal <sup>22</sup> , Christopher M. Lowery <sup>23</sup> , Erica Maletic <sup>24</sup> , Ashley N. Marranzino <sup>25</sup> , Beartiz E. Mejia-Mercado <sup>56</sup> , Thomas Morrow <sup>25</sup> , Lucien Nana Yobo <sup>21</sup> , Celeste Pallone <sup>2</sup> , Kurt Panter <sup>27</sup> , Molly Patterson <sup>28</sup> , Ally Peccia <sup>2</sup> , Thomas A. Ronge <sup>29</sup> , Ethan Roth <sup>0</sup> , Alice Staro <sup>31</sup> , Katherine Stelling <sup>5</sup> , Jordan P. Todes <sup>32</sup> , Man-Yin Tsang <sup>6</sup> , Scott T. Wieman <sup>1</sup> , Kevin Konrad <sup>45</sup> , Brendan Reilly <sup>2</sup> , Matthew Schrenk <sup>3</sup> , Maureen Walczak <sup>56</sup> , and Masako Tominaga <sup>1</sup> .         Berlower Mathematica Mathema		Overboarding capabilities up to 16,500 lb SWL	R	R	R	R	R	R
2 3 4 5 6 7 8			Overboarding capabilities up to 200,000 lb SWL	R	R	R	R	R	R
		ple	Seafloor and subseafloor characterization (multi-beam, back scatter, chirp sonar)	R	R	R	R	R	R
		eq	High resolution with precision navigation seafloor processes characterization (by AUV/ROV/HOV, and TowCam)	R	R	NMC	R	R	D
		at B	High resolution subseafloor imaging (<5 to ~200 m below seafloor)	D	R	R	D	R	R
		i ti ng ti	Deep subseafloor imaging (>1000 m below seafloor)	NMC	D	R	R	R	R
		Ase	Seafloor cabled arrays (sensors, power in focused areas like OOI RCA)	R	NMC	R	R	D	D
9		글릴	Refrigerated laboratory space	R	R	R	R	D	R
11		g pa	Radioisotope-safe laboratory space	R	D	R	R	D	D
12		olin Ca	Trace-metal clean laboratory space (e.g., lab van)	R	D	R	R	NMC	D
13	Tsang <sup>6</sup> , Scott T. Wieman <sup>1</sup> , Kevin Konrad <sup>4,5</sup> , Brendan Reilly <sup>2</sup> , Matthew Schrenk <sup>3</sup> , Maureen Walczak <sup>5,6</sup> ,	/es mb	Shipboard multi-sensor core logger	D	R	R	D	D	R
14 15		Sa	Shipboard CT/x-radiograph imaging	D	R	R	D	D	R
16		ortru	USBL (ultra short baseline) navigation and dynamic positioning for the widest range of vessel classes	R	R	R	R	R	R
17	^ = corresponding author	Resear Infrastru Seafloo	Polar aircraft	NMC	NMC	NMC	NMC	NMC	R
18 19	Institutional Affiliations: 1: Woods Hole Ceanographic Institution 2: Lamont-Doherty Earth Observatory, Columbia University 3: Michigan State University 4: University of Wavada, Las Yegas	Se Infe	Polar class < 5 capabilities and/or ice breaker	R	R	D	D	D	R
19			Dredging/wax coring (seafloor surface rock samples)	NMC	NMC	R	R	R	D
21 22			Dredging > 5000m water depths	NMC	NMC	R	R	R	NMC
23 24 25 26			Grab/Bio Samplers	R	D	NMC	NMC	NMC	R
	5: Oregon State University 6: University of Washington		Multi-coring/Slow-coring (sediment/water interface)	R	R	NMC	D	D	R
	7: Scripps Institution of Oceanography 8: Colorado School of Mines		Box/Soutar corers (large volume surface sediments)	R	R	NMC	NMC	NMC	R
27 28	Agency for Marine Science and Technology		Kasten corers (large volume up to 3 meters)	D	R	R	R	R	R
29 30			Gravity corers (2" or 4" diameter cores up to 20 m)	D	R	R	R	R	R
31 32		Ś	Piston corers (2" diameter corer up to >30 m)	NMC	D	D	D	D	R
33 34 35 36 37 38 39	14: College of Charleston	itie	Jumbo piston corers (4" diameter corer up to 30-40 m)	NMC	R	R	R	R	R
	13. University of two navel 15. Montan Technological University 17. Northern Illinois University 18. University of Maydand ©	lide	Giant piston corers (4" diameter corer up to 40-50 m)	NMC	R	R	D	D	R
		ab	Lander-style robotic drills** (3"+ diameter cores, holes up to ~200 m)	NMC	R	R	R	R	R
	19: George Mason University 20: University of California Santa Barbara	U U	Expanded capabilities of AUVs, including efficient access to a wide range of shallower water (10-4000m) depth	R	R	R	R	R	R
40 41	21: Texas A&M University, College Station	ļij	ROV/HOV Hosted Seafloor (rock) drill	D	NMC	NMC	R	R	NMC
42	ersity of Texas, Austin	đ	ROV/HOV Hosted Seafloor push corer	R	NMC	NMC	R	R	R
43 44		Sa	CORKs/seals/observatories/sensors	NMC	NMC	R	R	R	D
45 46 47	26: Florida State University	b	Gas/Fluid samplers (H2O, CH4, H2, Oxygen, etc.)	R	D	R	R	D	D
	28: Binghamton University	afle	Logging/geotechnical tools operable from ARF to access legacy holes	D	D	R	R	2010-10-10-10-10-10-10-10-10-10-10-10-10-	D
48 49	29: International Ocean Discovery Program, Texas A&M University 30: University of Alaska, Fairbanks	Š	Scientific Drilling platform/vessels (4"+ diameter cores, holes >1000 m, water depths at least > 6000m)	R	R	R	R	R	R
50 51	31: Boston University 32: University of Chicago								
51 52	an annaidh ar annailte		Blue : currently available - inc. elsewhere if not in US	1					
			Green : next emerging needs/low risk (low budget) ~ 1 yr funding cycle						
			Yellow : intermediate - during the corporate agreement period (~ 5vrs)						

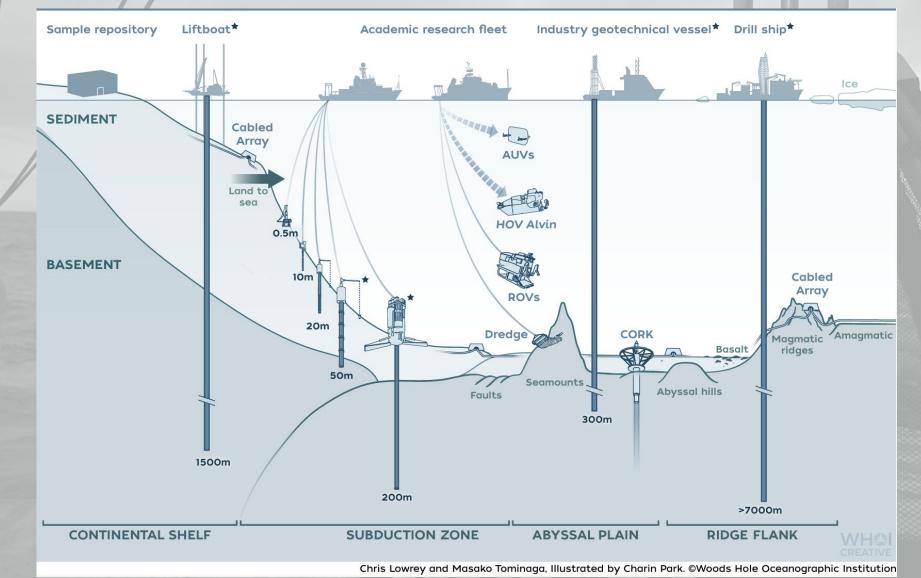
Orange : longer tern

Currently in revision to AGU Advances.

50 co-authors from 32 Institutions – many are ECRs from writing hackathon effort in Day-3.

### **WORKSHOP OUTCOMES:**

#### **ASSESSING SEAFLOOR/SUBSEAFLOOR SAMPLING CAPABILITIES**





## WORKSHOP OUTCOMES:

**Vessel's over-boarding capabilities** 

Reestablishing a longer piston coring system

Achieving 5000m+ dredging capability

Establishing US lander-style seafloor robotic coring systems

**Expanding underwater robotic capabilities (AUVs and ROVs)** 

Maximizing the value of returned samples

Advancing science through the torch relay of institutional knowledge



# ACKNOWLEDGEMENT



