

R/V L'Europe – A ship with new capabilities



R/V L'Europe

➤ A coastal twin-hull built in 1993

- ✓ Length : 29,60 m
- ✓ Width : 10,60 m
- ✓ Crew : 8 persons
- ✓ Science : 8 persons



➤ A major modernization in 2014 :

- ✓ New sensors for fish stock assessment cruises
- ✓ Installation of the new Ifremer Hybrid ROV



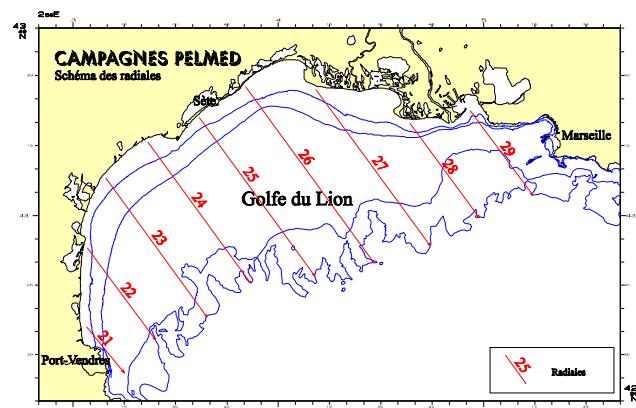
Pelagic species stock evaluation cruises

R/V l'Europe - PELMED cruises

Until now



- Echo-integration + 90 trawling + CTD
- ✓ Pelagic trawls + Marport/Scanmar
- ✓ SBES ER60-12/38/70/120/ 200 kHz
- ✓ Software : MOVIES+, CASINO

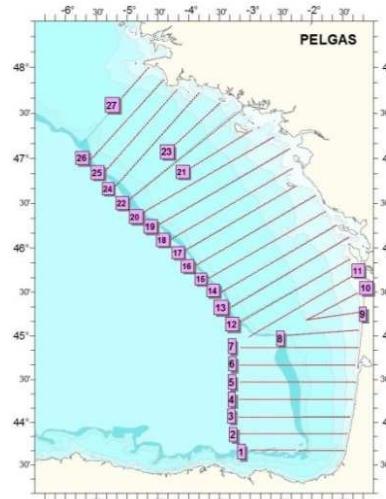


R/V Thalassa - PELGAS cruises



- Echo-integration + 68 trawling + CTD
- ✓ Pelagic trawls + Marport/Scanmar
- ✓ MBES Simrad ME70 - SMFH
- ✓ SBES ER60-12/38/70/120/200/333 kHz
- ✓ Software : HERMES-MOVIES-MOVIES3D-CASINO-PUPITRI-RAPTRI-SUMATRA

Objective is have similar tools
on L'Europe and Thalassa



Refit of R/V I'Europe

➤ Equipment upgrade

- ✓ Fishery MBES ME 70
- ✓ Fishery SBES 333kHz
- ✓ USBL positioning system
- ✓ Mobile equipment : ADCP, EM2040
- ✓ New MRU
- ✓ Scientific instruments

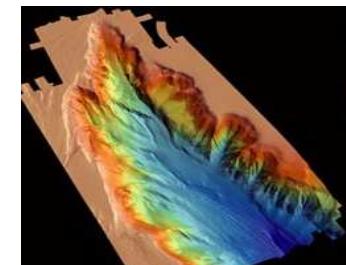


✓ Refit of IT network infrastructure

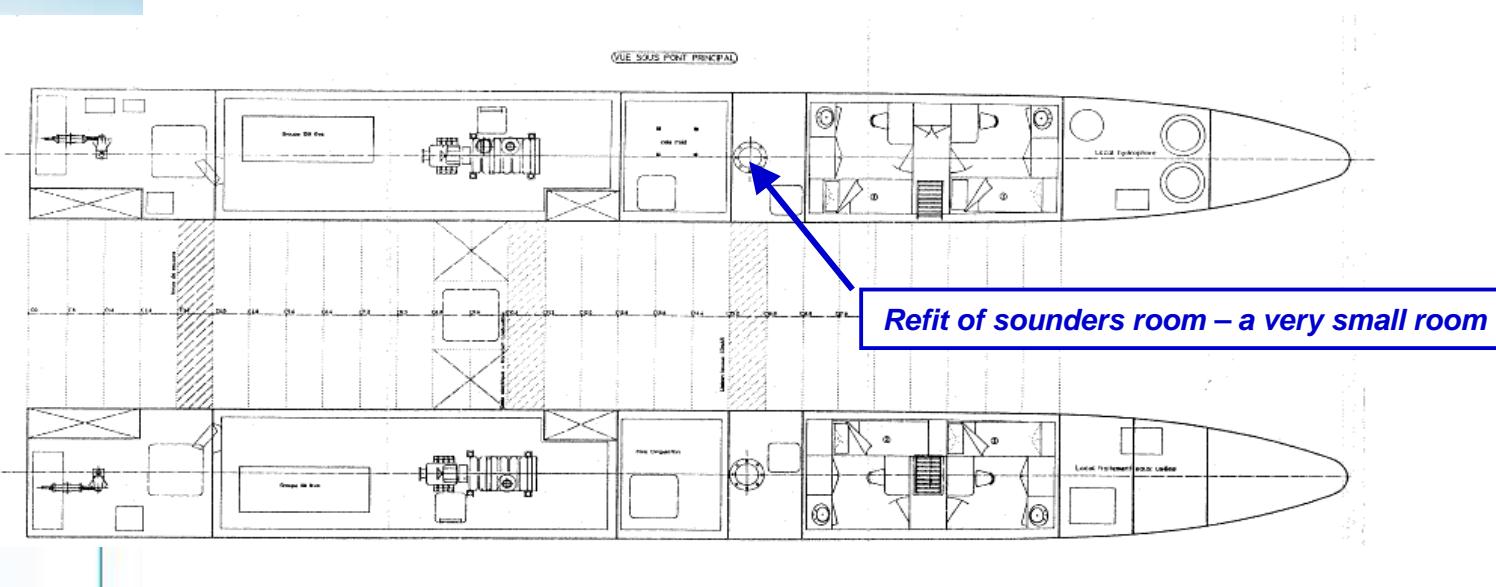
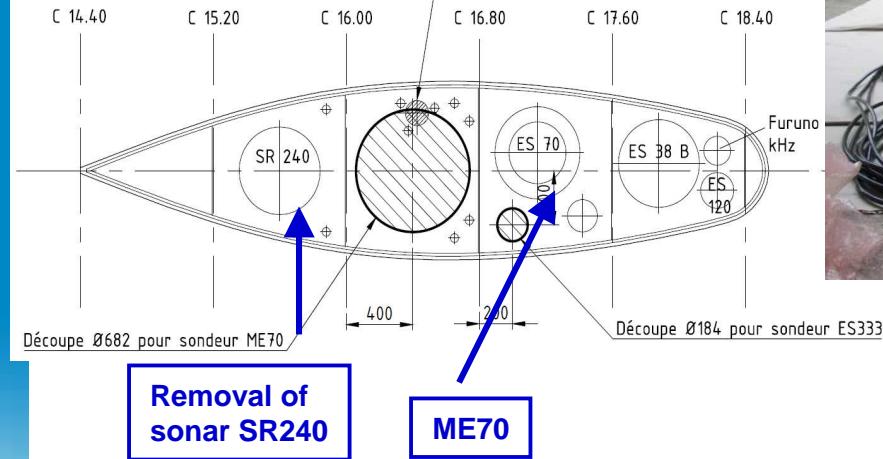
✓ VSAT installation



✓ Installation of new software



ME70 integration





ME70 cabinet



MARPORT system



ME70 power supply

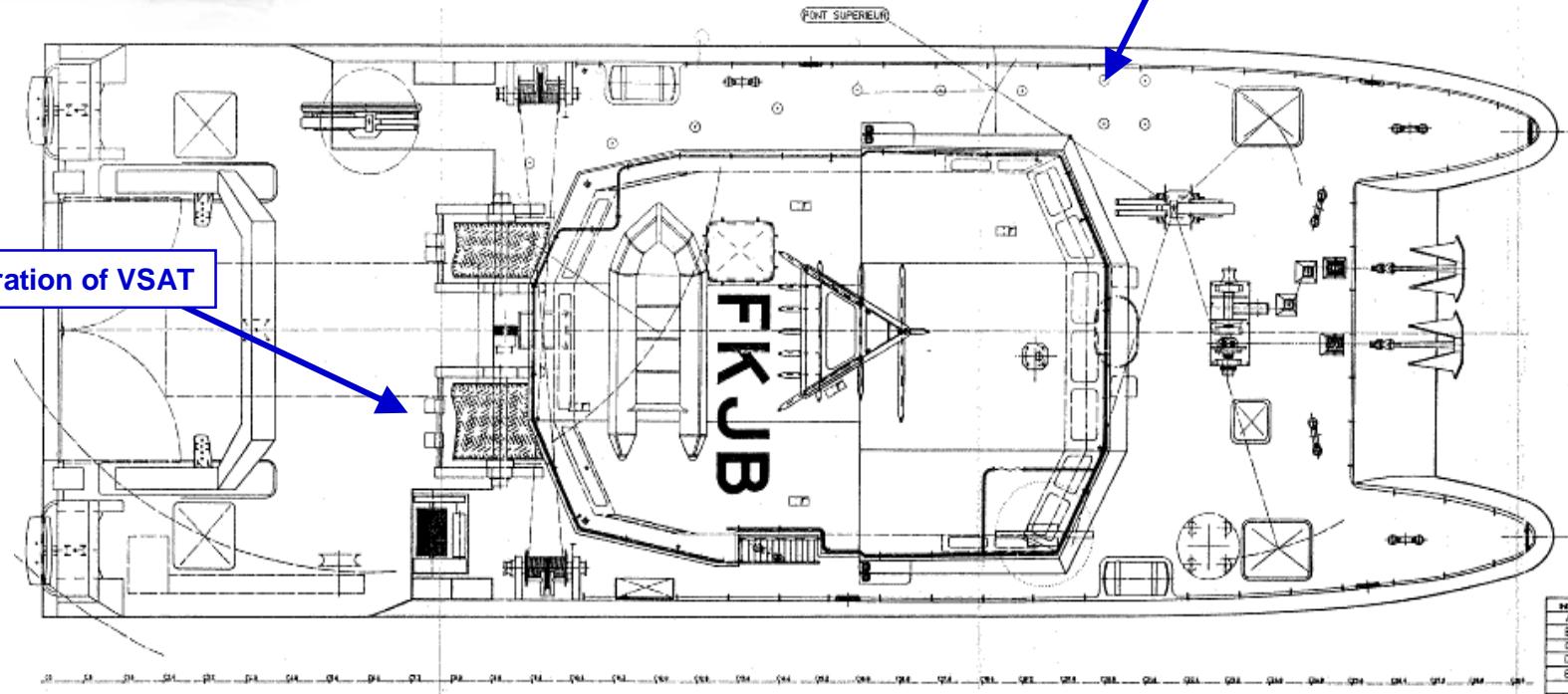
Upper deck



Intellian

Integration of VSAT

Calibration equipment for ME70

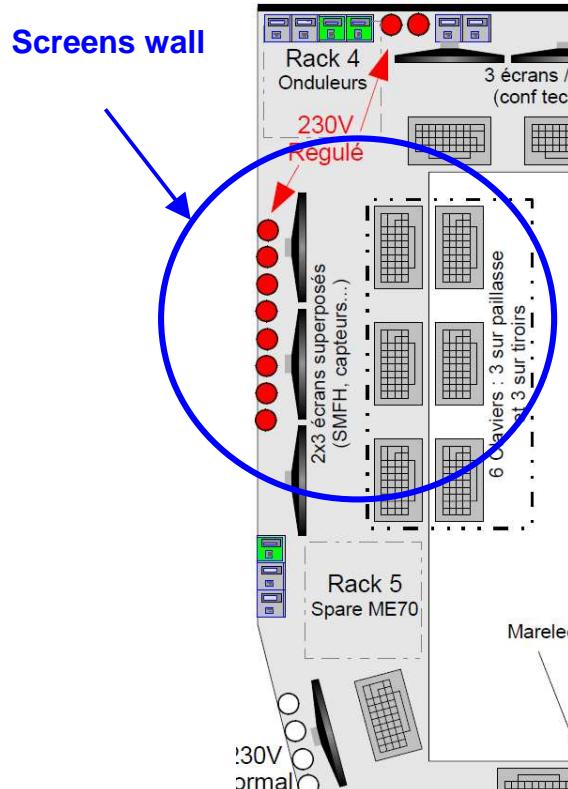


➤ Telepresence

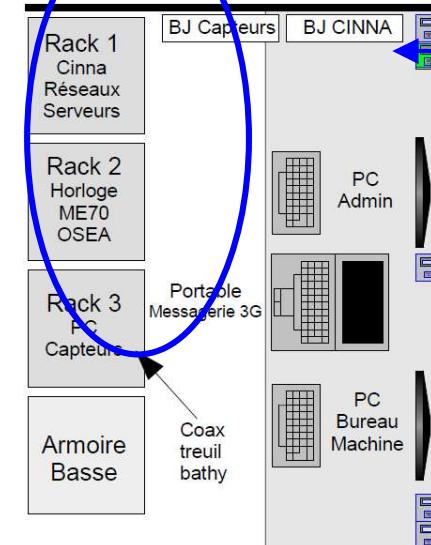
- ✓ Tele maintenance
- ✓ Tele assistance
- ✓ Tele processing



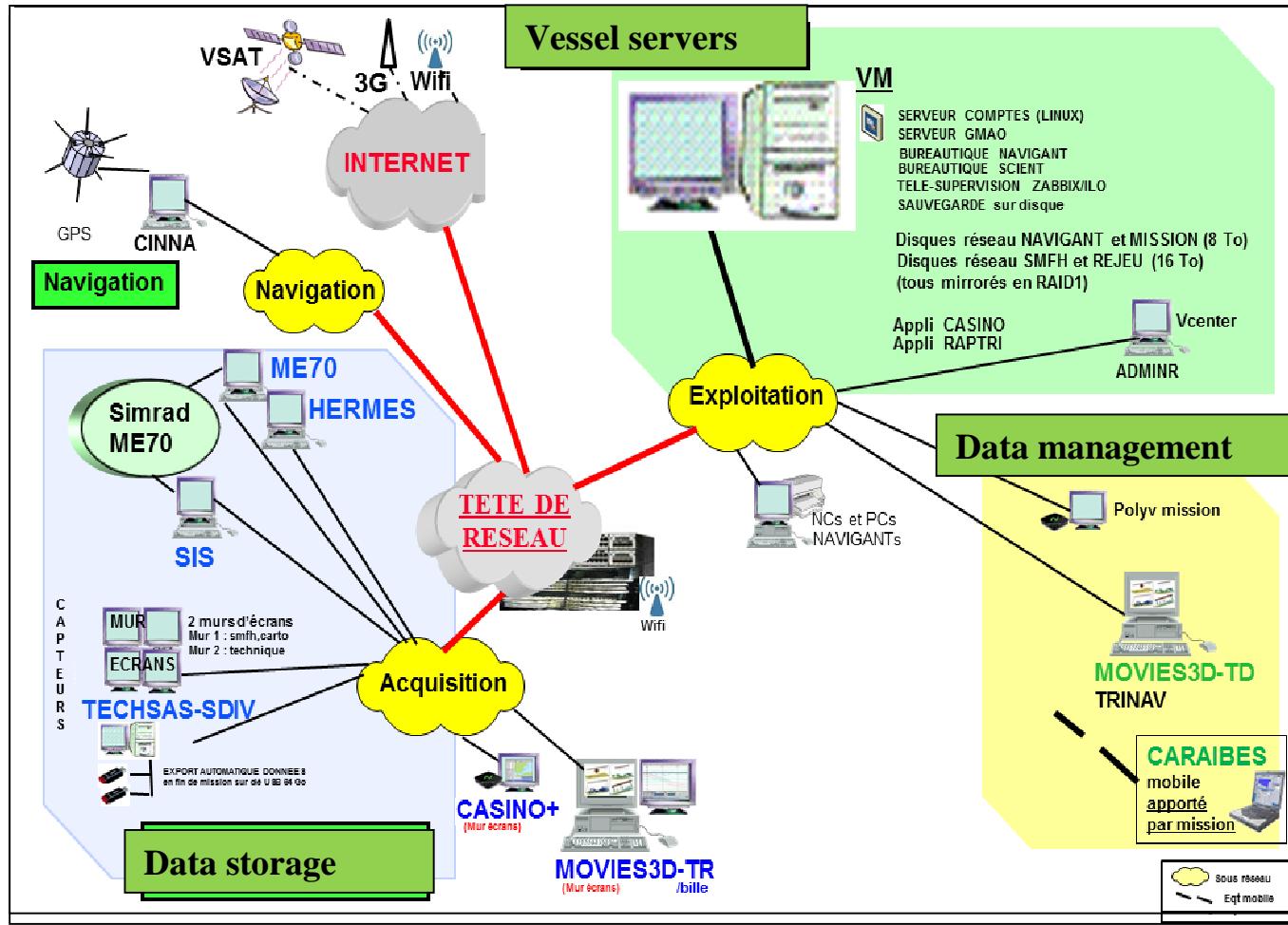
Scientific space



Vessel servers



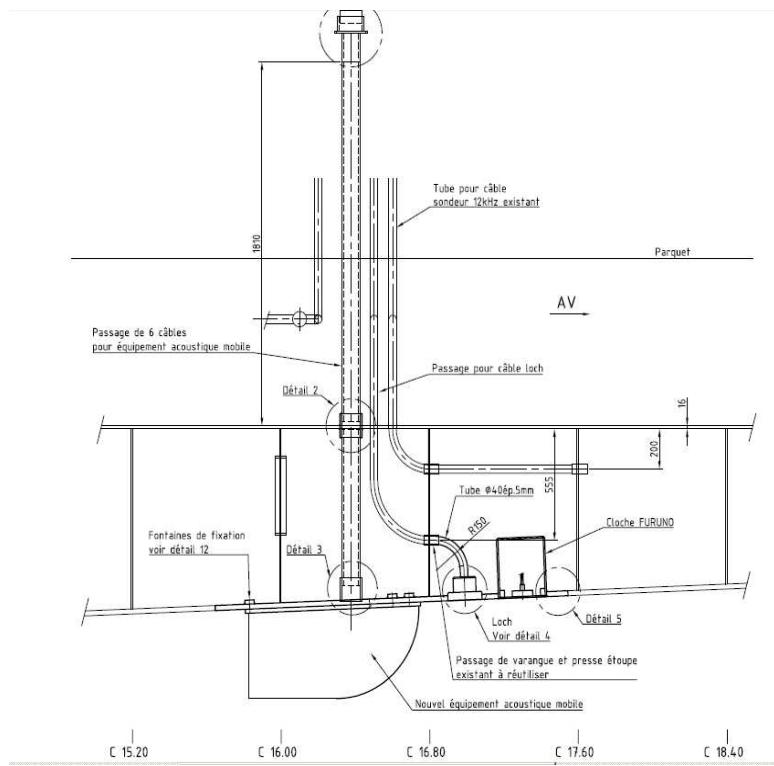
IT Network



Mobile equipment



EM2040



Missions	Mobile Equipment
AUV et HROV	GAPS, MATS, hydrophone
Fishery	ADCP
Geosciences	EM2040
Physics	ADCP + pinger 12kHz.



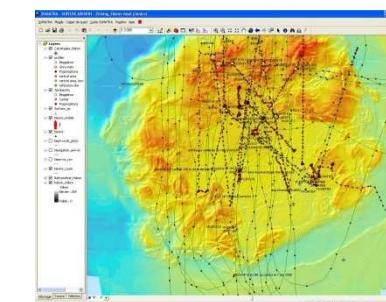
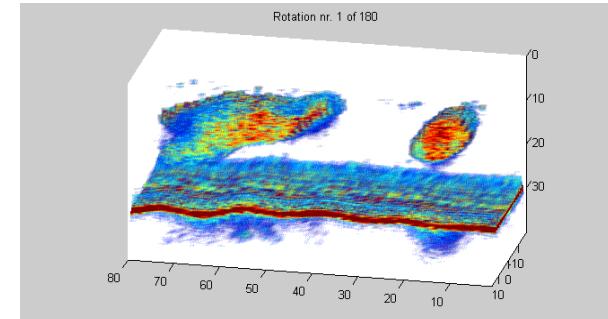
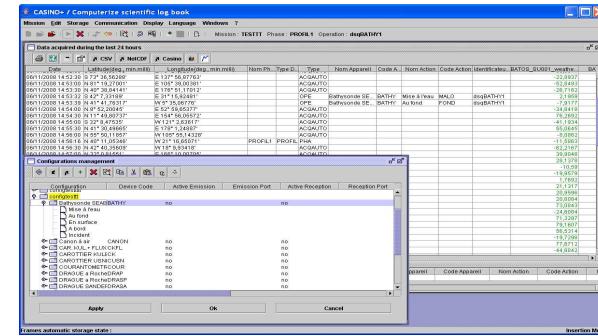
GAPS, MATS

Software

- Data acquisition (except ME 70)
 - ✓ TECHSAS for data acquisition + SEADATAVIEW for visualization
 - ✓ Supervision displays available on ship and on shore (scientists & operators)

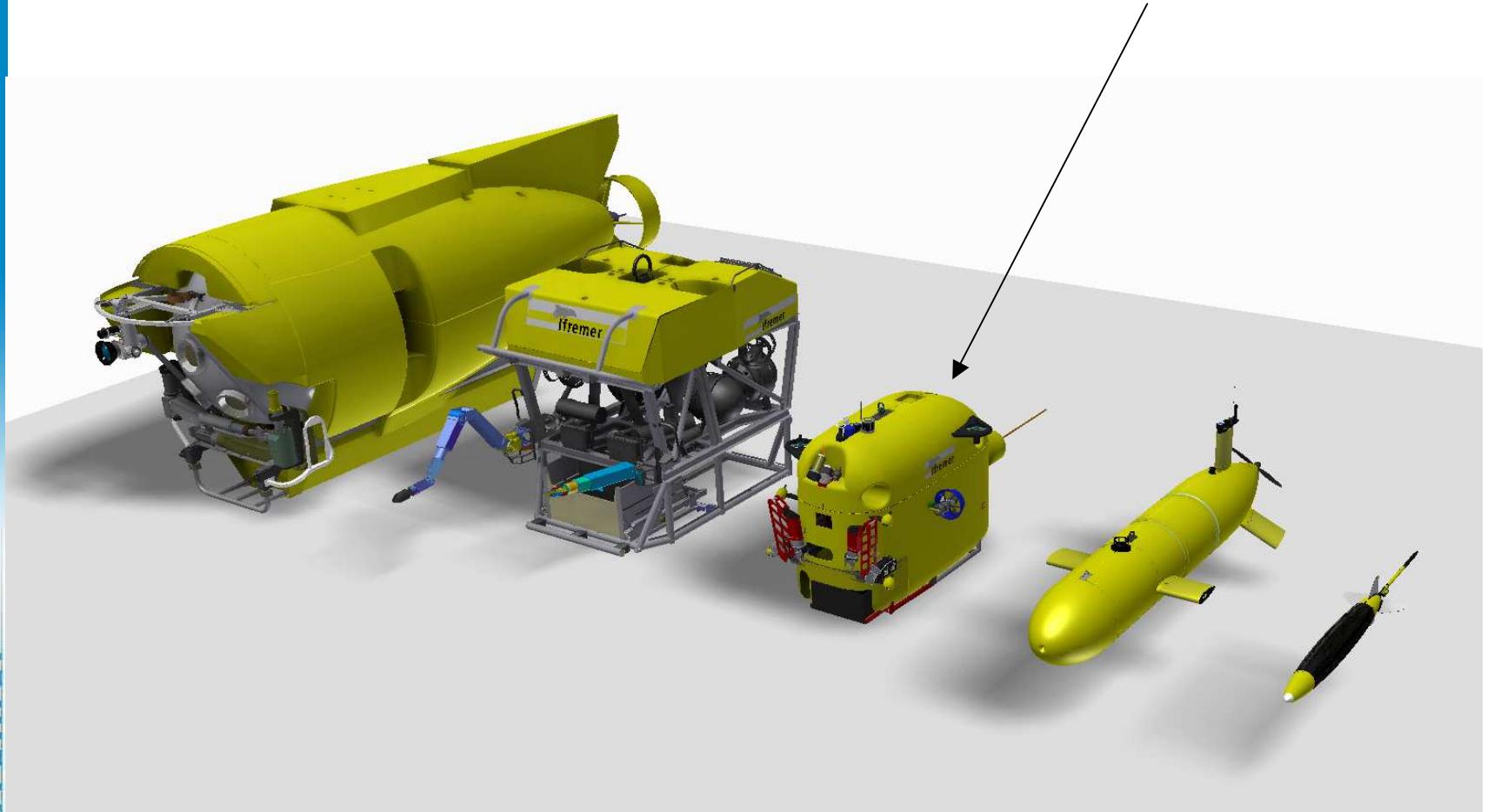
- ME 70 data acquisition and processing
 - ✓ HERMES, MOVIES 3D & MOVIES (idem *Thalassa*)
 - ✓ SVP Editor for sound speed profile

- Cruise follow-up
 - ✓ SUMATRA (idem *Thalassa*)
 - ✓ CASINO+ Logbook (idem *Thalassa*)



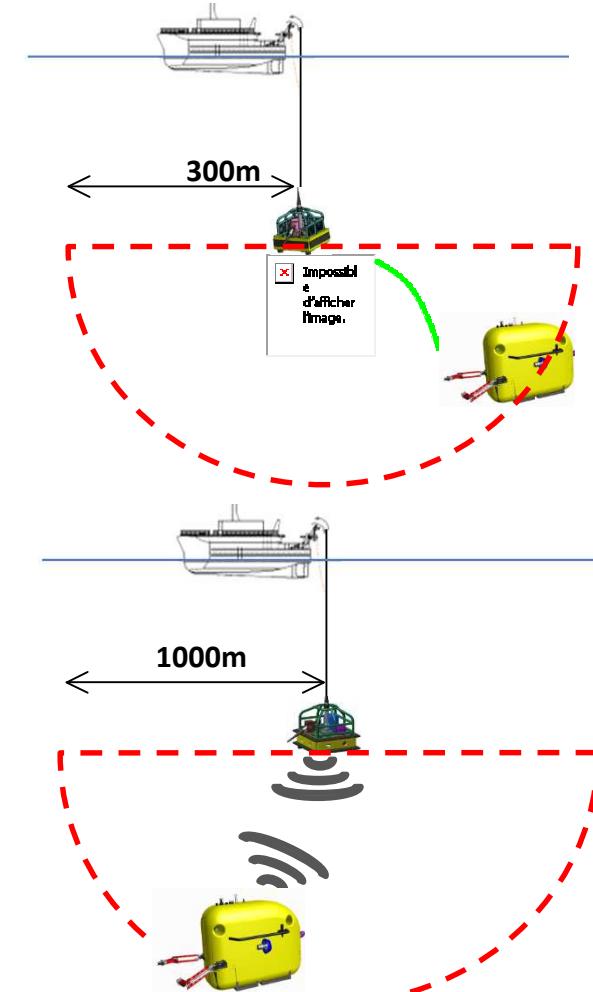
Family picture

Development of the Hybrid ROV
and integration on RV L'Europe



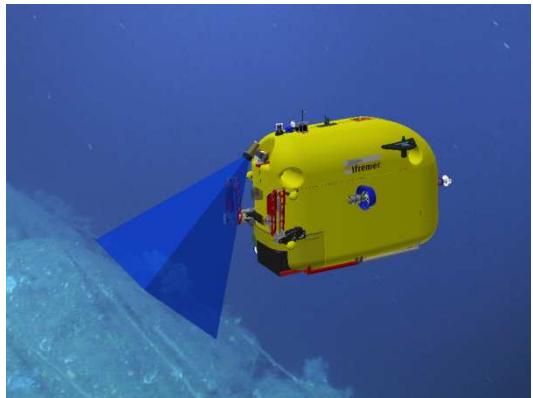
Concept

- Hybrid ROV = vehicle that can be deployed :
 - ✓ in ROV mode
 - ✓ In AUV mode
- Deployment from coastal ship without DP

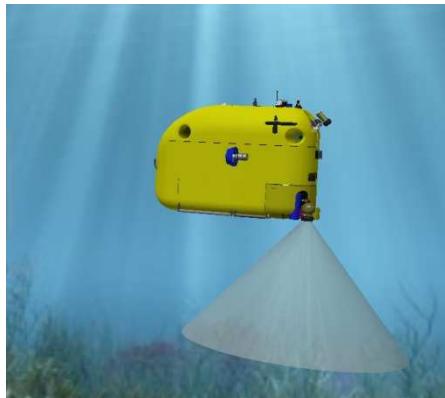


Missions

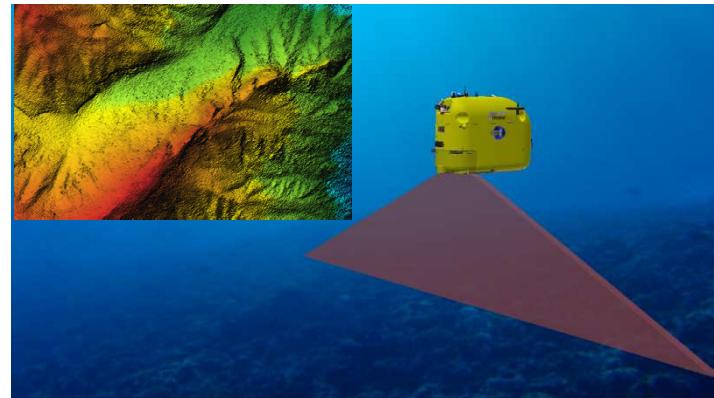
- **Inspection and mapping (AUV and ROV)**



Video HD

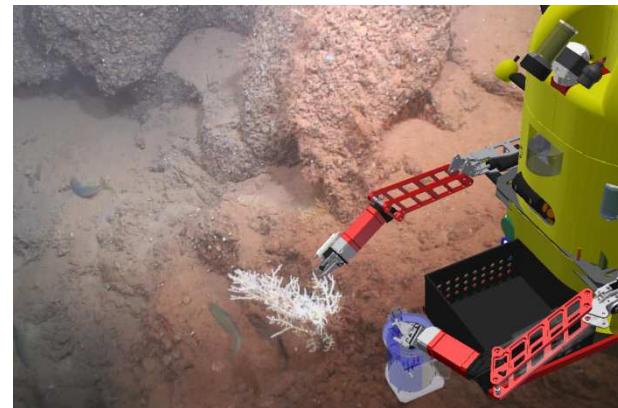
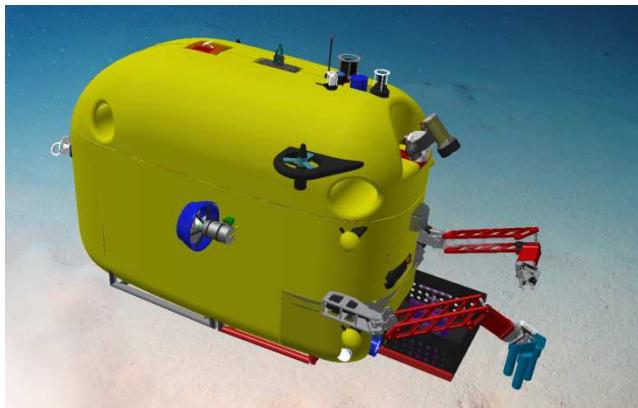


Optical mapping

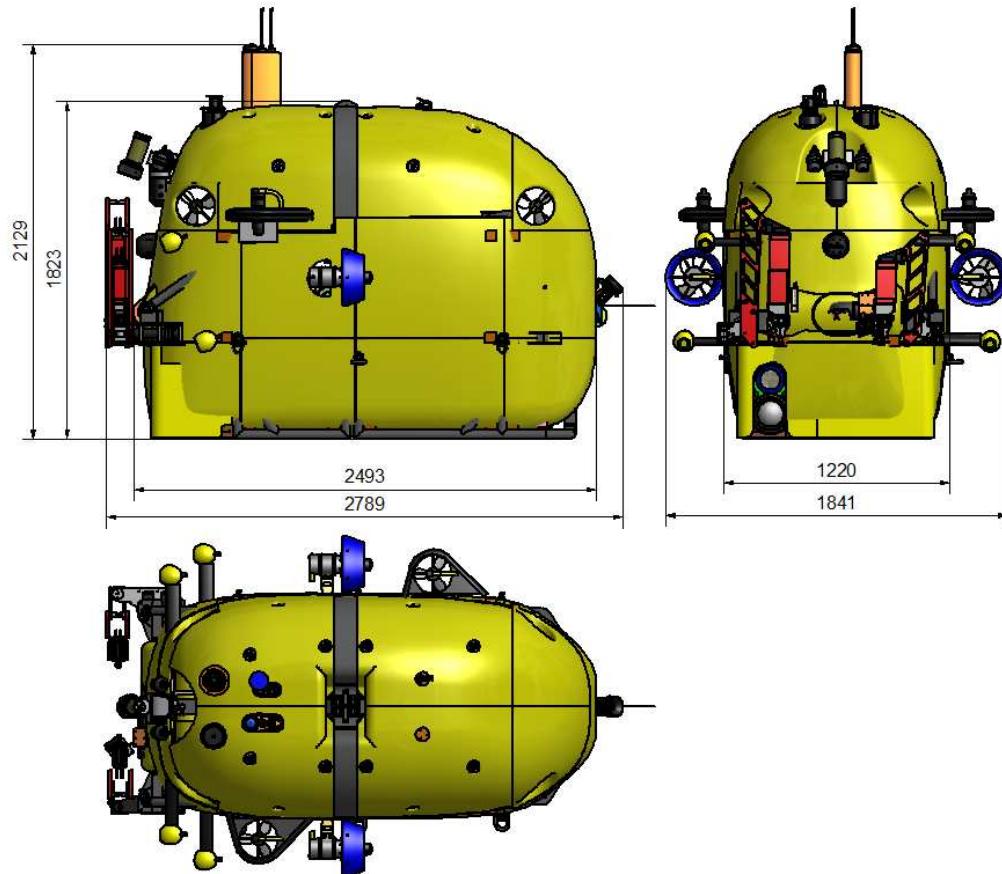


Acoustic mapping

- **Light sampling in ROV mode : coring, fauna, flora**



Vehicle



Energy : 20kWh

❖ 1 Battery Li-ion 13kWh@150Vdc



❖ 3 modules Li-ion 2kWh@48V



	Light configuration	Heavy configuration		
	masse dans l'air	In water weight	masse dans l'air	In water weight
HROV	1,6 tonne	- 5 daN	1,8 tonne	- 5 daN
Payload	80 kg	50 daN	220 kg	120 daN

Type of mission	autonomy
Inspection - 0,5nd	7h à 12h
Manipulation	8h à 12h
Survey at 1 knt	5h à 10h
Survey at 1,5 knt	3h à 4h
Survey at 2 knt	1h30 à 2h



Winch installation



Cable

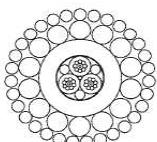
Diameter : 14,96mm

Length : 3000m

Mass : 812 kg/km

Weight in water : 660 kg/km

WL: 39kN, BS : 15,6kN



Winch

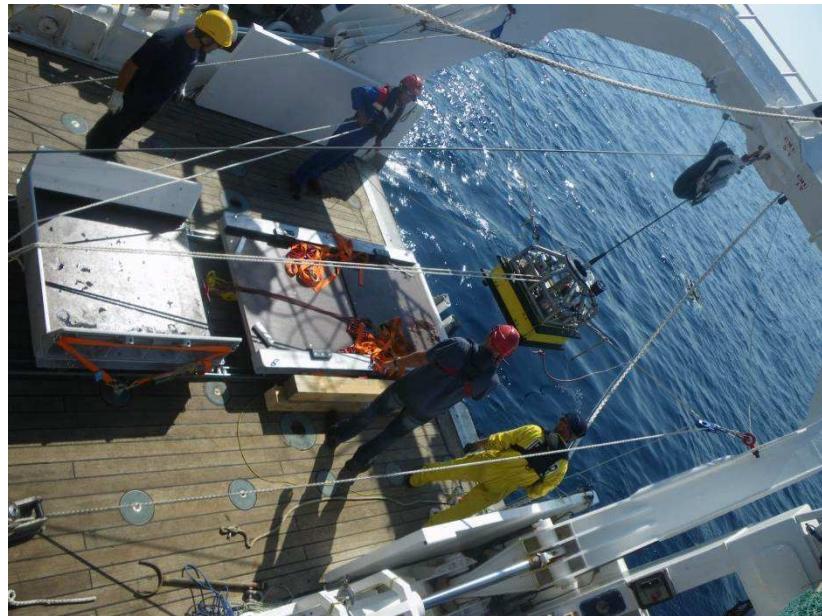
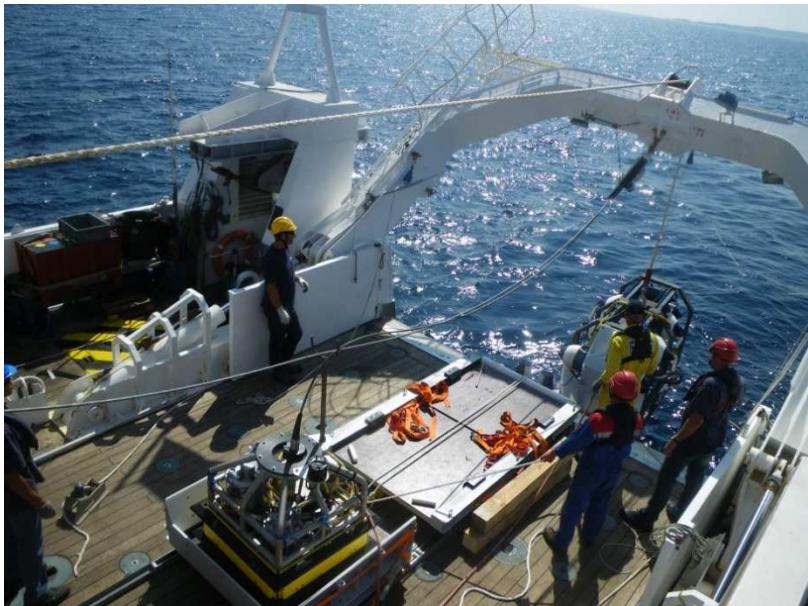
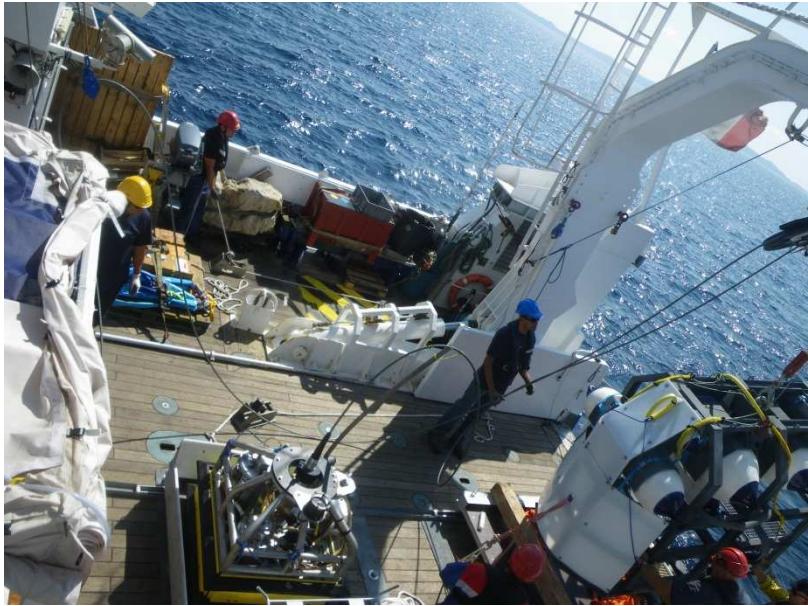
Mass : 3960 kg (without cable)

Masse : 6396 kg (with cable)

Dimensions: 2450*1980*1900 mm

SWL: 40 kN à 0,6 m/s

Deployment



Control room



3 persons : Pilot/co-pilot/scientist

- ✓ 1 server cabinet 4U
- ✓ 6 screens
- ✓ Surface Control System : Panel PC Tactil + Gamepad USB (x2)

Thanks for your attention